the three-dimensional computer model in accordance with a user-selected viewing direction, the apparatus comprising:

means for receiving data defining a user-selected viewing direction;

means for calculating the respective angle between the user-selected viewing direction and the respective viewing direction of each camera;

means for identifying the cameras having a viewing direction within a predetermined angle of the user-selected viewing direction as identified cameras;

means for comparing at least one camera characteristic affecting image data quality for each identified camera to determine differences therebetween;

means for selecting one of the identified cameras as a selected camera in dependence upon the determined differences;

means for processing input image data from the selected camera to define a representation of the object in the three-dimensional computer model; and

means for generating image data by rendering an image of the threedimensional computer model in accordance with the user-selected viewing direction, in which texture data based on input image data from the selected camera is rendered onto the representation of the object.

213. (Twice Amended) A signal conveying instructions for causing a programmable processing apparatus to become operable to perform a method according to any of claims 191, 201, 202 and 249.

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246. (Twice Amended) An image processing apparatus for processing image data defining a plurality of sequences of images, each from a respective camera, of an object moving in a scene to produce signals defining a representation of the object in a three-dimensional computer model, and to generate image data by rendering an image of the three-dimensional computer model in accordance with a user-selected viewing direction, the apparatus comprising:

a data receiver for receiving data defining a user-selected viewing direction; an angle calculator operable to calculate the respective angle between the user-selected viewing direction and the respective viewing direction of each camera;

a camera identifier operable to identify the cameras having a viewing direction within a predetermined angle of the user-selected viewing direction as identified cameras;

a camera characteristic comparer operable to compare at least one camera characteristic affecting image data quality for each identified camera to determine differences therebetween;

a camera selector operable to select one of the identified cameras as a selected camera in dependence upon the determined differences;

an object representation generator for processing input image data from the selected camera to define the selected representation of the object in the three-dimensional computer model; and

a renderer for generating image data by rendering an image of the threedimensional computer model in accordance with the user-selected viewing direction, in

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which texture data based on input image data from the selected camera is rendered onto the representation of each object.

data defining a plurality of sequences of images, each from a respective camera, of an object moving in a scene to produce signals defining a representation of the object in a three-dimensional computer model, and to generate image data by rendering an image of the three-dimensional computer model in accordance with a user-selected viewing direction, the apparatus comprising:

an object representation generator operable to process input image data from each respective camera to define a respective representation of the object in the three-dimensional computer model;

a data receiver for receiving data defining a user-selected viewing direction; an angle calculator operable to calculate the respective angle between the user-selected viewing direction and the respective viewing direction of each camera;

a camera identifier operable to identify the cameras having a viewing direction within a predetermined angle of the user-selected viewing direction as identified cameras;

a camera characteristic comparer operable to compare at least one camera characteristic affecting the image data quality for each identified camera to determine differences therebetween;